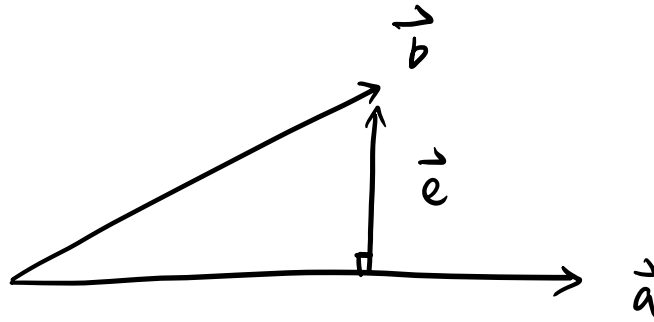


MIT : Gilbert Strang



$\text{proj}(\vec{b}) = P_b$  project  $\vec{b}$  onto  $\vec{a}$

$$P_b = x \vec{a}$$

↓  
multiple

$$\vec{e} = \vec{b} - x \vec{a}$$

求  $x$

$$\vec{e} \cdot \vec{a} = 0 \Rightarrow \vec{b} \cdot \vec{a} - x \underbrace{\vec{a} \cdot \vec{a}} = 0$$

$$x = \frac{\vec{a}^T \vec{b}}{\vec{a}^T \vec{a}}$$

↓ generalize to higher dimensional case

Ex. 3-dim

$P_b$  project  $b$  to the plane  
( $\vec{a}_1, \vec{a}_2$ )

$$\vec{e} = \vec{b} - x_1 \vec{a}_1 - x_2 \vec{a}_2$$

$$\vec{e} \cdot \vec{a}_1 = 0$$

$$\vec{e} \cdot \vec{a}_2 = 0$$

$$\begin{cases} \vec{b} \cdot \vec{a}_1 = x_1 \vec{a}_1 \cdot \vec{a}_1 + x_2 \vec{a}_2 \cdot \vec{a}_1 \\ \vec{b} \cdot \vec{a}_2 = x_1 \vec{a}_1 \cdot \vec{a}_2 + x_2 \vec{a}_2 \cdot \vec{a}_2 \end{cases}$$

$$\downarrow$$
$$A^T b = \begin{pmatrix} \vec{a}_1 \cdot \vec{a}_1 & \vec{a}_2 \cdot \vec{a}_1 \\ \vec{a}_1 \cdot \vec{a}_2 & \vec{a}_2 \cdot \vec{a}_2 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix}$$

$$A = \begin{pmatrix} | & | \\ a_1 & a_2 \\ | & | \end{pmatrix}$$

$$A^T \begin{matrix} a \\ || \\ \hline a_1^T \\ \hline a_2^T \end{matrix} \begin{pmatrix} | & | \\ a_1 & a_2 \\ | & | \end{pmatrix}$$

$a_1, a_2$   
是三分量向量  
here.

$A = a,$   
here

$$X = (A^T A)^{-1} A^T b$$

Q:

$$p = A\hat{x}$$

find  $\hat{x}$

$b - A\hat{x}$  is perpendicular  
to the plane  $(\vec{a}_1, \vec{a}_2)$

$$a_1^T (b - A\hat{x}) = 0$$

$$a_2^T (b - A\hat{x}) = 0$$

$$\begin{pmatrix} a_1^T \\ a_2^T \end{pmatrix} (b - \overset{\substack{\uparrow \\ \text{column vector}}}{A\hat{x}}) = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$A^T (b - A\hat{x}) = 0$$

$$e = b - A\hat{x} \quad \text{in} \quad N(A^T)$$

$$e \perp C(A) \quad \text{yes!}$$

$$A^T A \hat{x} = A^T b$$

general case

$A_{n \times n}$

$$\hat{x} = (A^T A)^{-1} A^T b$$

$$P_b = A \hat{x} = \frac{A (A^T A)^{-1} A^T b}{}$$

in one-dim

$$P_b = ax = a \frac{a^T b}{a^T a} = P b$$

projection operator on  $b$   
to give  $P_b$

$$A (A^T A)^{-1} A^T$$

project onto  $\text{col}(A)$  space

Q: can we reduce it to

$$\frac{A A^T}{} \frac{(A^T)^{-1} A^T}{} = I ?$$

NO!

$A$  is not square

Here,  $\text{col}(A)$  is NOT the whole space.

( $i=1, 2, \dots, n-1$ )

e.g.  $(n-1)$  vectors  $q_i$  with  $n$  components ( $n$ -dim)

proj  $b$  to the whole space :  $P = I$

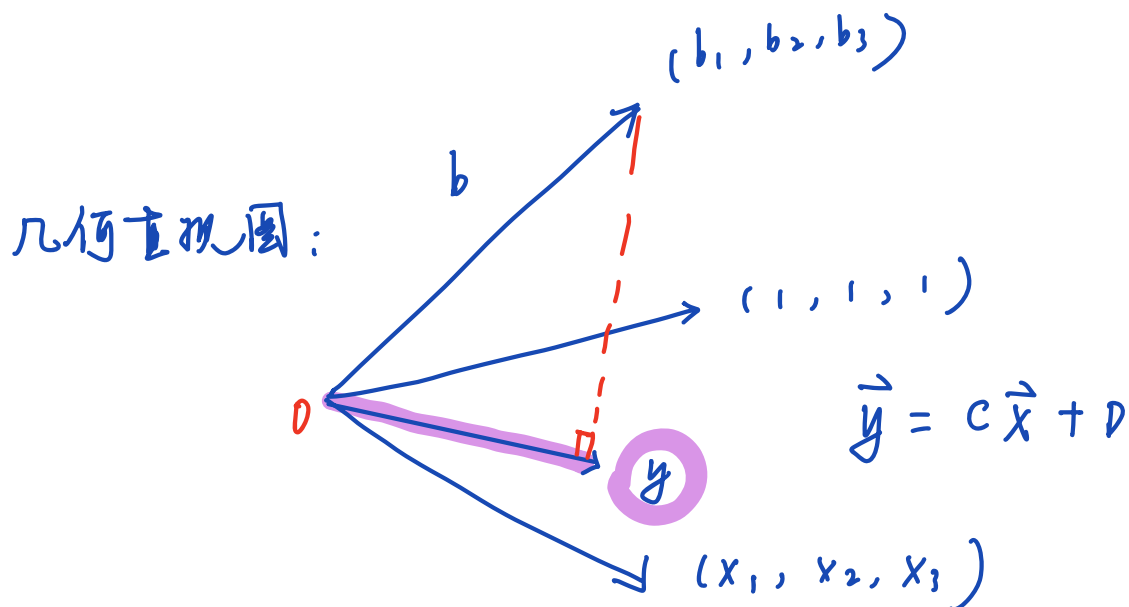
$$P = A (A^T A)^{-1} A^T$$

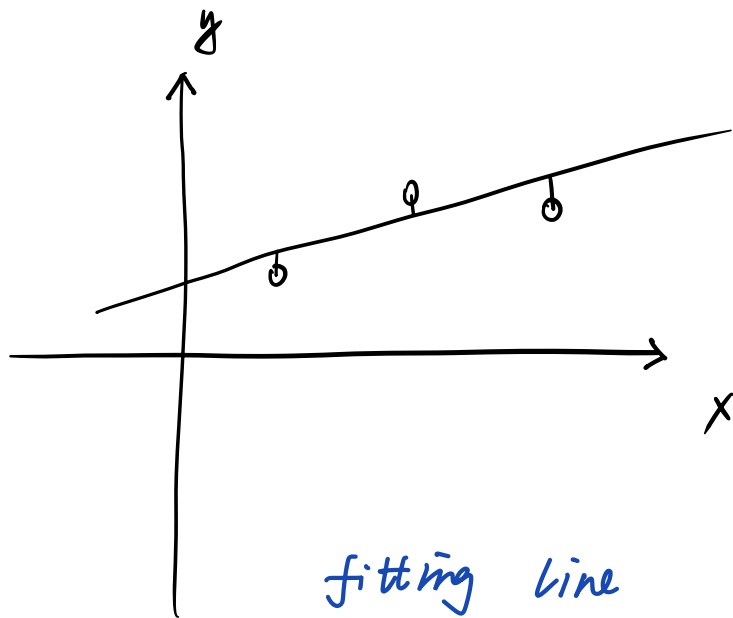
$$P = P^T$$

$$P^2 = P$$

proj once, into  $\text{col}(A)$

proj again, still there





$$y = cx + d$$

已知  $(x_1, b_1), (x_2, b_2), (x_3, b_3)$

$$\min |\vec{b} - \vec{y}|$$

is equivalent to the projection of  $b$   
onto  $y$

Solve  $c, d$

$$c \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} + d \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} = \begin{pmatrix} y_1 \\ y_2 \\ y_3 \end{pmatrix}$$

$$\begin{pmatrix} y_1 \\ y_2 \\ y_3 \end{pmatrix} = \begin{pmatrix} x_1 & 1 \\ x_2 & 1 \\ x_3 & 1 \end{pmatrix} \begin{pmatrix} c \\ d \end{pmatrix} = \boxed{A} (A^T A)^{-1} A^T b$$

$$\begin{pmatrix} C \\ D \end{pmatrix} = \left[ \begin{pmatrix} x_1 & x_2 & x_3 \\ \cdot & \cdot & \cdot \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ \cdot \\ \cdot \end{pmatrix} \right]^{-1}$$

$$\begin{pmatrix} x_1 & x_2 & x_3 \\ \cdot & \cdot & \cdot \end{pmatrix} \begin{pmatrix} b_1 \\ b_2 \\ b_3 \end{pmatrix}$$

最短的距离即投影出的 error

$$\vec{e} = \vec{b} - \vec{y} = \vec{b} - C\vec{x} - D \begin{pmatrix} \cdot \\ \cdot \\ \cdot \end{pmatrix}$$

问：如果已知 4 个点， $\{(x_1, b_1), (x_2, b_2), (x_3, b_3), (x_4, b_4)\}$

对上面的表达式作出怎样的修改？

$$\text{问：} \begin{pmatrix} x_1 & \cdot \\ x_2 & \cdot \\ x_3 & \cdot \\ x_4 & \cdot \end{pmatrix}$$

四维空间，四个 basis.

再好的拟合也有限，

应该如何进行？

问：\_ dim to \_ dim is 4-point case

Eg.  $a$  : Column vector ( $n$ -component)

$$a a^T = A_{n \times n} \quad \text{projection matrix}$$

$$\left( \begin{array}{c} \phi \end{array} \right) \left( \begin{array}{c} \overline{a^T} \end{array} \right)$$

rank 1,  $A$  still in  $\phi$

$\text{cov}(A)$  is a multiple of  $\phi$

e.g.

$$\begin{pmatrix} 1 \\ 2 \\ 4 \\ 5 \end{pmatrix} \quad (1 \ 2 \ 4 \ 5)$$

$$= \begin{pmatrix} 1 & 2 & 4 & 5 \\ 2 & 4 & 8 & 10 \\ 4 & 8 & 16 & 20 \\ 5 & 10 & 20 & 25 \end{pmatrix} \quad \text{multiple of } a$$

$$\left( \begin{array}{c} \phi \end{array} \right) \left( \begin{array}{c} \overline{a^T} \end{array} \right) X$$

$\downarrow$   $c$  number

$\downarrow$  multiple of  $\phi$

projection

$$T: \mathbb{R}^2 \rightarrow \mathbb{R}$$

$$T(v+w) = T(v) + T(w)$$

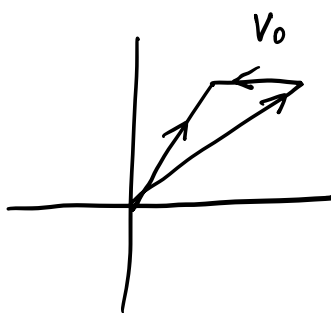
$$T(cv) = cT(v)$$

linear transformation

$$T(cv + dw) = cT(v) + dT(w)$$

Eg. 2

shift whole plane by  $v_0$



$T$  does to  $v$



$$T(v) = v_0 + v$$

$T$  not a linear trans

non-example

Another perspective :

e.g.  $W = I$ , prove the equivalence  
of the variation and equation

$$\min \|y - \hat{y}\|$$

$$\min \underline{\sum_i (y_i - (\beta_0 + \beta_1 x_i))^2} = f$$

$$\frac{\partial f}{\partial \beta_0} = -2 \sum_i [y_i - (\beta_0 + \beta_1 x_i)] = 0$$

$$\frac{\partial f}{\partial \beta_1} = -2 \sum_i x_i [y_i - (\beta_0 + \beta_1 x_i)] = 0$$

$$\sum_i y_i = \sum_i (\beta_0 + \beta_1 x_i)$$

$$\sum_i x_i y_i = \sum_i x_i (\beta_0 + \beta_1 x_i)$$



$$A^T y = A^T A \begin{pmatrix} \beta_0 \\ \beta_1 \end{pmatrix}$$

取例：已知四个点  $(x_1, y_1), \dots, (x_4, y_4)$

$$A = \begin{pmatrix} 1 & x_1 \\ 1 & x_2 \\ 1 & x_3 \\ 1 & x_4 \end{pmatrix}$$

$$\begin{pmatrix} 1 & 1 & 1 & 1 \\ x_1 & x_2 & x_3 & x_4 \end{pmatrix} \begin{pmatrix} y_1 \\ y_2 \\ y_3 \\ y_4 \end{pmatrix} = \begin{pmatrix} \sum y_i \\ \sum x_i y_i \end{pmatrix}$$

$$\begin{pmatrix} 1 & 1 & 1 & 1 \\ x_1 & x_2 & x_3 & x_4 \end{pmatrix} \begin{pmatrix} 1 & x_1 \\ 1 & x_2 \\ 1 & x_3 \\ 1 & x_4 \end{pmatrix} \begin{pmatrix} \beta_0 \\ \beta_1 \end{pmatrix} =$$

$$\begin{pmatrix} 4 & \sum x_i \\ \sum x_i & \sum x_i^2 \end{pmatrix} \begin{pmatrix} \beta_0 \\ \beta_1 \end{pmatrix} = \begin{pmatrix} 4\beta_0 + \sum x_i \beta_1 \\ \sum x_i \beta_0 + \sum x_i^2 \beta_1 \end{pmatrix}$$

$$\begin{pmatrix} \beta_0 \\ \beta_1 \end{pmatrix} = (A^T A)^{-1} A^T y$$